



# Numerical Simulation

Summer Semester 2015  
Lecturer: Prof. Dr. André Uschmajew  
Assistant: Bastian Bohn



## Exercise sheet 4.

Closing date **12.05.2015**.

### Theoretical exercise 1. (Dual Cones [6 points])

Let  $U$  be a Banach space and  $K \subseteq U$  a nonempty cone. Recall that the dual cone is defined by

$$K^+ := \{g \in U^* \mid g(u) \geq 0 \ \forall u \in K\}.$$

Furthermore for a fixed  $f \in U^*$ ,  $f \neq 0$ , let us define the cones

$$K_+ := \{u \in U \mid f(u) = 0\} \quad \text{and} \quad K_- := \{u \in U \mid f(u) \leq 0\}.$$

a) Prove that  $(K_+)^+ = \{\lambda f \mid \lambda \in \mathbb{R}\}$  and  $(K_-)^+ = \{\lambda f \mid \lambda \in (-\infty, 0]\}$ .

b) Let  $K$  be closed and let  $u \in U$  be such that

$$g(u) \geq 0 \quad \forall g \in K^+.$$

Prove that  $u \in K$ .

### Theoretical exercise 2. (Lagrange Duality [6 points])

Let  $U$  be a linear space and let  $Z$  be a normed space. Let  $f : C \rightarrow \mathbb{R}$  be a convex function where  $C \subseteq U$  is convex. Let furthermore  $G : U \rightarrow Z$  be convex and let  $K \subseteq Z$  be a nonnegative cone. Assume that the Slater condition holds and that

$$\mu_0 := \inf_{x \in C, G(x) \leq_K 0} f(x)$$

is finite.

Let us define  $\phi : K^+ \rightarrow \mathbb{R}$  by

$$\phi(z^*) := \inf_{x \in C} (f(x) + z^*(G(x))).$$

Recall the definition of  $\omega : \Gamma \rightarrow \mathbb{R} \cup \{-\infty\}$  from the lecture:

$$\omega(z) := \inf\{f(u) \mid u \in C, G(u) \leq_K z\}.$$

Here  $\Gamma = \{z \in Z \mid \exists u \in C \text{ s.t. } G(u) \leq_K z\}$ .

a) Prove that

$$\phi(z^*) = \inf_{z \in \Gamma} (\omega(z) + z^*(z)).$$

b) Prove that

$$\mu_0 = \sup_{z^* \in K^+} \phi(z^*)$$

and that the supremum on the right hand side is attained.

**Programming exercise 1.** (Newton-Lagrange Method)

**The programming exercises have to be done in C/C++. Please mail your code to [bohn@ins.uni-bonn.de](mailto:bohn@ins.uni-bonn.de) by 12th of May.**

Recall theoretical exercise 2 from sheet 1, i.e. consider the constrained minimization problem

$$\min_{(x,y) \in \mathbb{R}^2} f(x,y) := 3x^2 + y^2 \quad \text{such that} \quad g(x,y) := \frac{3}{2}x^2 + y = 2.$$

Implement a Newton-Lagrange minimization algorithm for this problem in the following way:

- Implement several functions which return the function values, the first derivatives and the second derivatives of  $f$  and  $g$  at a given point  $(x, y)$ .
- Implement Newton's root finding algorithm to detect the zeroes of the derivative of the Lagrangian  $\nabla \mathcal{L}$  where  $\mathcal{L}(x, y, \lambda) := f(x, y) + \lambda(g(x, y) - 2)$  since these are potential minimizers. The algorithm should stop when the right hand side in the Newton iteration has an  $\ell_2$  norm smaller than  $10^{-15}$ . You should implement this algorithm on your own and not take a ready-to-use algorithm from a numerical library.
- For the solution of the upcoming linear equation system you may use a solver from a numerical standard library (e.g. `gsl_linalg_LU_solve` from the gsl [<http://www.gnu.org/software/gsl/>]) or your own linear equation system solver.
- Use starting values  $x = 5000, y = -3000$  and  $\lambda = 400$ . What point does the algorithm converge to? How many iterations does it need? Plot the  $\ell_2$  norm of the right hand side vector in the Newton algorithm as a function of the current iteration number in a semilogarithmic plot (e.g. with *gnuplot*).