

# V4E2 - Numerical Simulation

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## Exercise sheet 11.

To be handed in on **Thursday, 20.07.2017.**

Let  $\mathcal{M}$  denote the set of real valued  $N \times N$  matrices. We denote by  $\alpha^a$  the vector

$$\alpha^a = (a, \dots, a)^\top.$$

Let  $\mathcal{A}^N$  be a compact set of vectors  $\alpha = (\alpha_1, \dots, \alpha_n)^\top$ . We define the set of minimizers associated with  $F(x)$  by

$$\mathcal{A}_x := \{\alpha \in \mathcal{A}^N : B(\alpha)x - c(\alpha) = F(x)\}$$

where

$$F(x) := \min_{\alpha \in \mathcal{A}^N} (B(\alpha)x - c(\alpha))$$

and it's component wise set

$$\mathcal{A}_{x,i} := \{a \in \mathcal{A} : [B(\alpha^a)x - c(\alpha^a)]_i = [F(x)]_i\}$$

where

$$F_i(x) = \min_{\alpha \in \mathcal{A}^N} [B(\alpha)x - c(\alpha)]_i.$$

The assumptions of Theorem 45 are:

- (H1) For every  $\alpha \in \mathcal{A}^n$ , the matrix  $B(\alpha)$  is monotone ( $B$  is invertible and  $B^{-1}$  is component wise  $\geq 0$ )
- (H2) When  $\mathcal{A}$  is an infinite compact set, the functions  $\alpha \in \mathcal{A}^N \rightarrow B(\alpha) \in \mathcal{M}$  and  $\alpha \in \mathcal{A}^N \rightarrow c(\alpha) \in \mathbb{R}^N$  are continuous.

We assume for  $\alpha = (\alpha_1, \dots, \alpha_N) \in \mathcal{A}^n$  that  $B_{i,j}(\alpha)$  and  $c_i(\alpha)$  depend only on  $\alpha_i$ .

**Exercise 1.** (Consider the setup of Theorem 45)

- (i) Show under the assumptions from Theorem 45 it holds, that for every  $v \in \mathbb{R}^N$  and

$$d(\alpha_i^{v+w}, A_{v,i}) \rightarrow 0, \quad w \in \mathbb{R}^N, \|w\| \rightarrow 0$$

with  $\alpha_i^{v+w} \in A_{v+w,i}$ . Hint: Prove by contradiction. Define the set

$$K_\delta := \{a \in \mathcal{A} : d(a, A_{v,i}) \geq \delta > 0\}$$

and consider properties of

$$m_\delta := \inf_{a \in K_\delta} [B(a)v - c(a)]_i$$

- (ii) Show that using (i) one can find  $\alpha^{k,*} \in A_{v^k}$  such that for  $\alpha^{k+1} = \alpha^{v^k}$

$$B(\alpha^{k+1}) - B(\alpha^{k,*}) \rightarrow 0$$

for  $k \rightarrow \infty$ . Hint: use  $\alpha^{v^k} = \alpha^{v+h_k}$ ,  $h_k := v^k - v^*$ .

**Exercise 2.** An introductory example playing Tic-Tac-Toe is presented in

Sutton, R., Barto, A. Reinforcement Learning, MIT Press, 1998.

beginning from page 10. Code that allows simulations is provided here: <https://github.com/ShangtongZhang/reinforcement-learning-an-introduction/blob/master/chapter01/TicTacToe.py> Discuss the following issues stated there. You can try to modify the code to obtain ideas.

- Self-Play: Suppose, instead of playing against a random opponent, the reinforcement learning algorithm described above played against itself, with both sides learning. What do you think would happen in this case? Would it learn a different policy for selecting moves?
- Symmetries: Many Tic-Tac-Toe positions appear different but are really the same because of symmetries. How might we amend the learning process described above to take advantage of this? In what ways would this change improve the learning process? Now think again. Suppose the opponent did not take advantage of symmetries. In that case, should we? Is it true, then, that symmetrically equivalent positions should necessarily have the same value?
- Greedy Play: Suppose the reinforcement learning player was greedy, that is, it always played the move that brought it to the position that it rated the best. Might it learn to play better, or worse, than a nongreedy player? What problems might occur?

The book is available via <http://incompleteideas.net/sutton/book/bookdraft2017june19.pdf>