



# Scientific Computing I

Winter Semester 2013 / 2014  
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## Exercise sheet 10.

Closing date **7.1.2014**.

### Theoretical exercise 1. (Kronecker-product [7 points])

Let  $A \in \mathbb{R}^{k \times l}$  and  $B \in \mathbb{R}^{m \times n}$ . Then, the Kronecker-product of the matrices  $A$  and  $B$  is given by

$$A \otimes B = \begin{pmatrix} a_{11}B & a_{12}B & \dots & a_{1l}B \\ a_{21}B & a_{22}B & \dots & a_{2l}B \\ \vdots & & \ddots & \\ a_{k1}B & a_{k2}B & \dots & a_{kl}B \end{pmatrix} \in \mathbb{R}^{km \times ln}.$$

Show that the following relations hold for  $\alpha \in \mathbb{R}, A \in \mathbb{R}^{k \times l}, B \in \mathbb{R}^{m \times n}, C \in \mathbb{R}^{k \times l}, D \in \mathbb{R}^{l \times s}, E \in \mathbb{R}^{n \times r}$ .

- a)  $(\alpha A) \otimes B = A \otimes (\alpha B) = \alpha(A \otimes B)$
- b)  $(A \otimes B)^T = A^T \otimes B^T$
- c)  $(A + C) \otimes B = A \otimes B + C \otimes B$
- d)  $(A \otimes B)(D \otimes E) = (AD) \otimes (BE)$
- e)  $(A \otimes B)^{-1} = A^{-1} \otimes B^{-1}$

### Theoretical exercise 2. (Structure of mass- and stiffness-matrices [7 points])

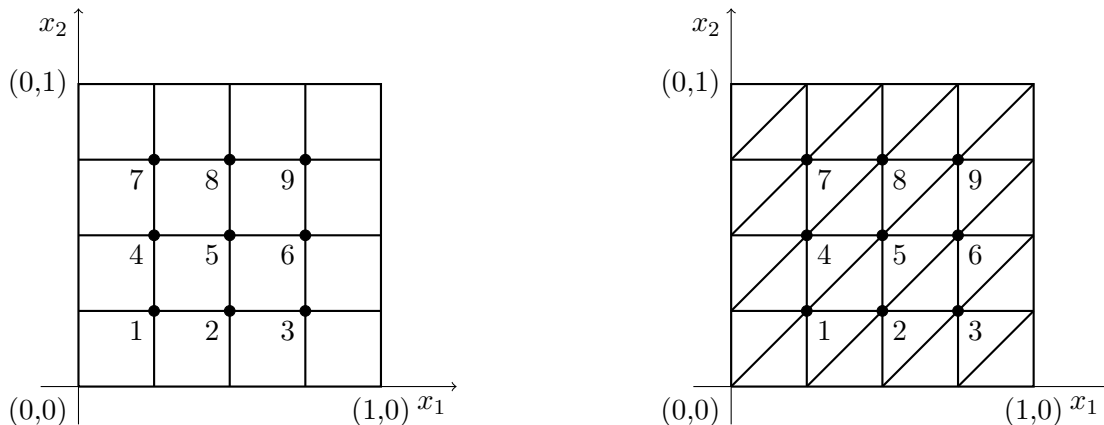


Figure 1: Triangulation for bilinear elements (left) and for linear triangle elements (right)

We are given the Poisson problem

$$-\Delta u = 1 \quad \text{on} \quad (0, 1)^2$$

with homogeneous boundary conditions  $u = 0$  on  $\partial(0, 1)^2$ . See Fig. 1 for two possible triangulations of  $(0, 1)^2$  suited for bilinear elements and linear triangle elements. We denote the basis functions that belong to the nine inner vertices by  $(\varphi_i)_{i=1}^9$ .

- a) Show that for the bilinear element case, the following holds: The mass matrix  $M \in \mathbb{R}^{9 \times 9}$  with

$$(M)_{ij} = (\varphi_i, \varphi_j)_{L_2((0,1)^2)} \quad \text{for } i, j = 1, \dots, 9$$

can be written as the Kronecker-product of two  $\mathbb{R}^{3 \times 3}$ -matrices.

- b) Show that for both the bilinear element case and the linear triangle element case, the following holds: The stiffness matrix  $K \in \mathbb{R}^{9 \times 9}$  with

$$(K)_{ij} = (\nabla \varphi_i, \nabla \varphi_j)_{L_2((0,1)^2)} \quad \text{for } i, j = 1, \dots, 9$$

can be written as the sum of two Kronecker-products of two  $\mathbb{R}^{3 \times 3}$ -matrices.

- c) Generalize above results to  $n^2$  quadratic patches or  $2n^2$  triangles.

**Theoretical exercise 3.** (Bonus: Fundamental Lemma of Calculus of Variations [ 5 points ])

Let  $\Omega \subset \mathbb{R}^n$  be an a connected and open set and  $u \in L_{1,loc}(\Omega)$ . Furthermore,  $k \in \mathbb{N}_0$ . If  $D^\alpha u = 0$  for an  $\alpha \in N_0^n$  with  $|\alpha| = k$ , then  $u$  is equal almost everywhere to a polynomial of order  $k - 1$ .

Prove the Lemma stated above with the hints you got in your tutoring session.

**The closing date for submission of the programming exercise is the 14th of January!**

**Programming exercise 1.** (Incorporation of boundary conditions and solving a PDE [20 points])

After assembling the full stiffness matrices over the last weeks we now have to incorporate the Dirichlet and Neumann boundary conditions. In a final step we will then put all pieces together to result with a Finite Element program.

**Tasks:**

- a) [10 points] Implement the member function `void incorporateBoundaryConditions(CSRMatrix* stiffnessMatrix, double* loadVector)` of the class `PDE`. As parameters you pass a pointer to the already assembled stiffness matrix and the load vector.

First, iterate over the `neumannEdgeIndices` of `Mesh` which lie on the finest level, i.e. for which `isRefined` is `false`. For every corresponding edge  $e$  you have to compute the Jacobi determinant  $J$  of the linear transformation from the “interval”  $[0, 1]$  on the x-axis (i.e. y-coordinate is 0) to the edge  $e$  such that  $(0, 0)$  is mapped to the first edge-node and  $(1, 0)$  is mapped to the other one. Therefore  $|J|$  is just the length of the edge  $e$ . Then call `calcBoundaryIntegral` of `Basis` for every node of  $e$  (with the corresponding local node index as parameter) with  $|J| \cdot a$  as `factor` and add this value at the correct position of the load vector. Here,  $a$  is the value of the Neumann boundary for the edge  $e$ .

Now, set  $g := 10^{30} \cdot n \cdot M$  with  $n$  being the number of nodes in the mesh and  $M$  being the largest absolute value of an entry of the stiffness matrix. Then, iterate over the `DirichletEdgeIndices` of `Mesh` which lie on the finest level. For every node index  $i$  of a node of the corresponding edge  $e$  add  $g$  to the diagonal entry  $K_{ii}$  of the stiffness matrix and add  $g \cdot b$  to the corresponding load vector position. Here,  $b$  is the value of the Dirichlet boundary for the edge  $e$ .

**Remark:** For your convenience the member functions `addToDiagonal(int i, double value)` and `getMaxAbsEntry()` have been added to the implementation of the `CSRMatrix` class.

- b) [10 points] Complete your finite element program: Implement the member function `void solvePDEFromFile(const char* infilename, int numMeshRefinements, int maxIt, double eps, const char* outfilename)` of PDE. The function should read the file specified by `infilename`, refine the created mesh `numMeshRefinements` times, assemble the global stiffness-matrix and load vector, incorporate the boundary conditions, solve the resulting system with a CG-algorithm for CSR-matrices (exit after `maxIt` iterations or if the relative error is below `eps`) and write the result to a VTK-file called `outfilename`.

Here, the VTK-file should like this:

```
# vtk DataFile Version 3.0
PDE solution
ASCII
DATASET UNSTRUCTURED_GRID
POINTS N double
coord0 coord1 0.0
coord2 coord3 0.0
:
CELLS E X
L node1 node2 node3 node4 node5 node6
L node7 node8 node9 node10 node11 node12
:
CELL_TYPES E
T
T
:
POINT_DATA N
SCALARS u(x,y) double 1
LOOKUP_TABLE default
s1
s2
:
```

Here,  $N$  denotes the number of nodes. `coord0` and `coord1` denote the x- and y-coordinates of the first node. The other nodes follow analogously.  $E$  denotes the number of elements.  $L$  denotes the number of local basis functions (i.e. 3 for the linear and 6 for the quadratic Lagrange basis) and  $X = E \cdot (L + 1)$ . `node1` denotes the index of the first node of the first element. `node4 node5 node6` and `node10 node11 node12` are optional and have only to be given if the corresponding element is quadratic. The other elements follow analogously. The number  $T$  is 5 for linear elements and 22 for quadratic elements (this is a VTK-internal numbering). It has to appear  $E$  times. `s1` is the value of the solution of the PDE at node 1. The other node values follow analogously.

Test your implementation:

- a) Enable quadrature (use the seven point rule) and call your function `void solvePDEFromFile(const char* infilename, int numMeshRefinements, int maxIt, double eps, const char* outfilename)` for the file `SampleGrid.txt`. This resembles the Poisson problem

$$\Delta u = 1$$

on  $[0, 1]^2$  with  $u = 0$  on  $\partial[0, 1]^2$  discretized by quadratic Lagrange elements. The mesh should be refined six times. The CG-algorithm should be called with parameters `maxIt`=  $10^6$  and `eps`=  $10^{-20}$ . Visualize the result (e.g. by paraview).

- b) To compare the diagonally preconditioned CG-algorithm to a standard CG algorithm run the same routine for a non-preconditioned CG algorithm (you can just set all entries of `diag` to 1 instead of calling `genDiag` in `pcCG` of `CSRMatrix`). Compare the number of iterations.

**Feel free to use your own code or the incomplete code from the website. Note that the closing date for submission of the programming exercise is the 14th of January.**