



# Scientific Computing 1

Winter term 2017/18  
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## Sheet 10

Submission on **Thursday, 11.1.18.**

### Exercise 1. (The Stokes Equation)

Let  $\Omega \subset \mathbb{R}^n$  be an open, bounded and convex domain with smooth boundary  $\partial\Omega$  and normal unit vector  $n: \partial\Omega \rightarrow \mathbb{R}^n$ . The motion of an incompressible viscous fluid with velocity field  $u: \Omega \rightarrow \mathbb{R}^n$  can be modeled with the PDE

$$\begin{aligned}\Delta u + \nabla p &= -f && \text{in } \Omega, \\ \operatorname{div} u &= 0 && \text{in } \Omega, \\ u &= u_0 && \text{on } \partial\Omega.\end{aligned}$$

Here,  $p: \Omega \rightarrow \mathbb{R}$  is the pressure density,  $f: \Omega \rightarrow \mathbb{R}^n$  is an external force field and  $\Delta$  is the componentwise Laplacian.

- a) Assume that a (strong) solution  $(u, p)$  exists. Show that the boundary condition  $u_0$  must satisfy

$$\int_{\partial\Omega} u_0 \cdot n \, dS = 0.$$

From now on, we consider homogeneous boundary conditions  $u_0 = 0$ . Moreover, for a solution  $(u, p)$ ,  $p$  is only determined up to an additive constant, so we additionally enforce

$$\int_{\Omega} p \, dx = 0.$$

We proceed to the weak formulation: Define

$$X = H_0^1(\Omega)^n, \quad M = \left\{ q \in L^2(\Omega) : \int_{\Omega} q \, dx = 0 \right\},$$

$$\begin{aligned}a(u, v) &= \int_{\Omega} \operatorname{Tr}[(Du)^\top(Dv)] \, dx, \\ b(v, q) &= \int_{\Omega} q \operatorname{div} v \, dx\end{aligned}$$

with  $Du = [\partial_j u_i]_{i,j=1}^n$  the Jacobian matrix of  $u$ . We get a saddle point problem:  
Find  $(u, p) \in X \times M$  such that

$$\begin{aligned}a(u, v) + b(v, p) &= (f, v)_{L^2(\Omega)} \\ b(u, q) &= 0\end{aligned}$$

is satisfied for all  $v \in X, q \in M$ .

- b) Show that  $a(u, v)$  is elliptic on the whole space  $X$ , with respect to the  $H^1(\Omega)^n$ -norm

$$\|u\|_{1,n} = \left( \sum_{i=1}^n \|u_i\|_{H^1(\Omega)}^2 \right)^{1/2}.$$

c) The form  $b(v, q)$  induces an operator  $B': M \rightarrow X'$  via

$$(v, B'q)_{X, X'} = b(v, q).$$

Show that  $B'$  restricted to  $M \cap H^1(\Omega)$  reduces to the negative weak gradient operator  $q \mapsto -\nabla q \in L^2(\Omega)^n \subset X'$ .

(8 points)

**Exercise 2.** (unstable discretization)

We consider a finite element discretization of the Stokes equation for  $\Omega = [0, 1]^2$  with the standard rectangular mesh  $\mathcal{T}_h = \{T_{ij}\}_{i,j=0}^{m-1}$ , where  $h = 1/m$  and

$$T_{ij} = [ih, (i+1)h] \times [jh, (j+1)h]$$

for  $i, j = 0, \dots, m$ . Moreover, we choose piecewise continuous, bilinear elements for the velocity and piecewise discontinuous, constant elements for the pressure:

$$\begin{aligned} X_h &= \{v \in X : v_1|_T, v_2|_T \in \mathcal{Q}(T) \text{ for } T \in \mathcal{T}_h\}, \\ M_h &= \{q \in M : q|_T \text{ constant for } T \in \mathcal{T}_h\}. \end{aligned}$$

Note that a function  $v \in X_h$  is completely determined by its values at the nodes  $(ih, jh)$  for  $i, j = 1, \dots, m-1$ . To simplify notation, we set  $v = (v_1, v_2) = (u, w)$  and  $u_{ij} = u(ih, jh)$ ,  $w_{ij} = w(ih, jh)$ , as well as  $q_{i+1/2, j+1/2} = q((i+1/2)h, (j+1/2)h)$ .

a) Show that for  $v \in X_h$ ,  $q \in M_h$  one has

$$\int_{\Omega} q \operatorname{div} v \, dx = h^2 \sum_{i,j=1}^{m-1} [u_{ij}(\nabla_1 q)_{ij} + w_{ij}(\nabla_2 q)_{ij}],$$

with difference quotients

$$\begin{aligned} (\nabla_1 q)_{ij} &= \frac{1}{2h} [q_{i+1/2, j+1/2} + q_{i+1/2, j-1/2} - q_{i-1/2, j+1/2} - q_{i-1/2, j-1/2}], \\ (\nabla_2 q)_{ij} &= \frac{1}{2h} [q_{i+1/2, j+1/2} - q_{i+1/2, j-1/2} + q_{i-1/2, j+1/2} - q_{i-1/2, j-1/2}]. \end{aligned}$$

b) Show that the kernel of the operator  $B'_h: M_h \rightarrow X'_h$  defined via

$$(v, B'_h q)_{X_h, X'_h} = \int_{\Omega} q \operatorname{div} v \, dx$$

is

$$\ker B'_h = \operatorname{span}\{q^*\}$$

with

$$q_{i+1/2, j+1/2}^* = \begin{cases} 1 & i+j \text{ odd,} \\ -1 & i+j \text{ even.} \end{cases}$$

We replace  $M_h$  with the reduced space  $R_h = \{q \in M_h : (q, q^*)_{L^2(\Omega)} = 0\}$ , to obtain injectivity of  $B'_h$  on  $R_h$ . However, this is still not enough to obtain stability in the limit  $h \rightarrow 0$ .

c) (Bonus exercise)

Show that there exists a constant  $C > 0$  such that

$$\inf_{q \in R_h} \sup_{v \in X_h} \frac{b(v, q)}{\|v\|_{1,2} \|q\|_{L^2(\Omega)}} \leq Ch.$$

(8+4 points)