



# Numerical Algorithms

Winter semester 2018/2019  
Prof. Dr. Marc Alexander Schweitzer  
Denis Duesseldorf



## Exercise sheet 9. Submission on Monday, 2018-12-18, after lecture.

### Exercise 29. (Cubic Hermite splines)

Consider a partitioning of  $[a, b]$  into  $N$  intervals using nodes

$$a = x_0 < x_1 < \dots < x_N = b.$$

Assume that data  $f_i, i = 0, \dots, N$  are given. For a) and b) further assume that  $f'_i, i = 0, \dots, N$  are given.

a) Let  $a = 0, b = 1$  and  $N = 1$ . Show that

$$\alpha_1(t) := 2t^3 - 3t^2 + 1$$

$$\alpha_2(t) := -2t^3 + 3t^2$$

$$\alpha_3(t) := t^3 - 2t^2 + t$$

$$\alpha_4(t) := t^3 - t^2$$

$$\Rightarrow p(t) := f_0\alpha_1(t) + f_1\alpha_2(t) + f'_0\alpha_3(t) + f'_1\alpha_4(t)$$

yields a solution  $p \in \mathcal{P}_3$  of the Hermite interpolation problem

$$p(0) = f_0, \quad p(1) = f_1, \quad p'(0) = f'_0, \quad p'(1) = f'_1.$$

b) For arbitrary  $x_i$  we define  $p_i(x)$  on each  $[x_{i-1}, x_i], i = 1, \dots, N$  via

$$h_i := x_i - x_{i-1}, \quad t_i(x) := (x - x_{i-1})/h_i, \quad \alpha_{k,i} := \alpha_k(t_i(x))$$

with  $i = 1, \dots, N, k = 1, \dots, 4$ .

Use  $\alpha_{k,i}$  to construct  $p_i \in \mathcal{P}_3$  such that

$$p_i(x_{i-1}) = f_{i-1}, \quad p_i(x_i) = f_i, \quad p'_i(x_{i-1}) = f'_{i-1}, \quad p'_i(x_i) = f'_i.$$

c) With a) and b) we can now construct the Hermite Spline interpolant. With given data  $f_i$  and  $f'_0, f'_N$ , the missing values  $f'_i, 0 < i < N$  are chosen such that the resulting piecewise polynomial

$$p(x) = p_i(x) \quad x \in [x_{i-1}, x_i]$$

is twice continuously differentiable.

Show that  $p \in C^1$  even without a proper choice of  $f'_i$ . Compute  $p_i^{(2)}$  in  $x_{i-1}, x_i$  and establish a system of linear equations for  $f'_i$  to yield  $p \in C^2$ .

d) How does the linear system from c) change when requiring natural boundary conditions

$$p''_1(a) = p''_N(b) = 0$$

instead of the Hermite boundary conditions  $p'_1(a) = f'_0, p'_N(b) = f'_N$ ?

(4 Points)

**Exercise 30.** (B-Splines)

The  $0 < n$  B-Spline basis functions  $N_{i,p}, i = 1, \dots, n$  of polynomial degree  $p$  corresponding to a so called knot vector

$$\Xi = (\xi_1, \xi_2, \dots, \xi_{n+p+1}), \quad \xi_1 \leq \xi_2 \leq \dots \leq \xi_{n+p+1}$$

are typically given via the recursion

$$N_{i,0}(\xi) = \begin{cases} 1 & \xi_i \leq \xi < \xi_{i+1} \\ 0 & \text{otherwise} \end{cases},$$

$$N_{i,p}(\xi) = \frac{\xi - \xi_i}{\xi_{i+p} - \xi_i} N_{i,p-1}(\xi) + \frac{\xi_{i+p+1} - \xi}{\xi_{i+p+1} - \xi_{i+1}} N_{i+1,p-1}(\xi).$$

with the convention of  $\frac{0}{0} = 0$  in case where  $\xi_i = \xi_{i+p}, N_{i,p-1} = 0$  or  $\xi_{i+p+1} = \xi_{i+1}, N_{i+1,p-1} = 0$ , see also c).

Using these functions and so called control points  $B_i \in \mathbb{R}^d, i = 1, \dots, n$  the piecewise-polynomial B-spline curve is given as

$$C(\xi) = \sum_{i=1}^n N_{i,p}(\xi) B_i.$$

Show the following properties.

- a) If the knots are distinct,  $\forall i : \xi_i < \xi_{i+1}$ , then the B-spline basis admits the explicit representation

$$N_{i,p} = (\xi_{i+p+1} - \xi_i) \sum_{j=i}^{i+p+1} \left( \prod_{k=i, k \neq j}^{i+p+1} (\xi_j - \xi_k) \right)^{-1} (\xi_j - \xi)_+^p$$

where

$$(\xi_j - \xi)_+^p = \begin{cases} (\xi_j - \xi)^p & \xi_j > \xi \\ 0 & \text{otherwise} \end{cases}.$$

*Hint:* Show that the functions defined this way satisfy the recursion given for the B-spline basis.

- b)  $N_{i,p}$  depends only on the local knots

$$\{\xi_i, \dots, \xi_{i+p+1}\}$$

- c) The local support property

$$N_{i,p}(\xi) = 0, \quad \xi \notin [\xi_i, \xi_{i+p+1})$$

holds.

In particular

$$\xi_i = \xi_{i+p+1} \Rightarrow N_{i,p} \equiv 0$$

and, if  $\xi \in [\xi_j, \xi_{j+1})$ ,

$$(i < j - p) \vee j < i \quad \Rightarrow \quad N_{i,p}(\xi) = 0.$$

- d) The basis is positive inside its support

$$N_{i,p}(\xi) > 0, \quad \xi \in (\xi_i, \xi_{i+p+1}).$$

e) The B-spline basis functions are piecewise polynomials

$$N_{i,p}(\xi) = \sum_{j=i}^{i+p} N_{i,p}^j(\xi) N_{j,0}(\xi)$$

with  $N_{i,p}^j$  being polynomials of degree at most  $p$ .

f) If  $z = \xi_{i+1} = \dots = \xi_{i+p} < \xi_{i+p+1}$  then

$$N_{i,p}(z) = 1, \quad \text{and} \quad N_{j,p}(z) = 0 \quad \forall j \neq i.$$

g) If  $z$  occurs  $k$  times among  $\xi_i, \dots, \xi_{i+p+1}$  then

$$N_{i,p} \in C^{p-k}.$$

In particular  $N_{i,p} \in C^{p-1}$  if  $\xi_i$  are distinct.

h) The B-spline basis forms a partition of unity on  $[\xi_{p+1}, \xi_{n+1})$

$$\sum_{i=1}^n N_{i,p}(\xi) = 1, \quad \xi \in [\xi_{p+1}, \xi_{n+1}).$$

i) If  $\xi \in [\xi_j, \xi_{j+1})$  with  $p+1 \leq j \leq n$  then

$$C(\xi) = \sum_{i=j-p}^j N_{i,p}(\xi) B_i$$

j) If  $z = \xi_{i+1} = \dots = \xi_{i+p} < \xi_{i+p+1}$  with  $1 \leq i \leq n$  then

$$C(z) = B_i.$$

k) If  $z$  occurs  $k$  times in  $\Xi$  then  $C$  has continuous derivatives to order  $p-k$ .

(8 Points)

**Programming exercise 10.** (Splinatoraptor)

A recent excursion into the Siebengebirge brought to light remains of what is believed to be a petrified fossil. For the reconstruction of the shape of the original animal the  $20 \times 10$  unit wide excavation site is covered with a grid. A logical reordering of the coordinates of the fossil remains yields the following  $c_i = (x_i, y_i)$ .

$i$	0	1	2	3	4	5	6	7	8	9	10	11	12	13
$x_i$	13	11.5	10	11	9	6	0	6	10.5	13	15	15	16	19
$y_i$	0	0	2	4	5.5	6	5	7	7	7.5	7	9	10	9
$i$	14	15	16	17	18	19	20	21	22	23	24	25	26	
$x_i$	17	16.5	16	15	15	15.5	14.5	15	14	13	12	11	13	
$y_i$	8.5	8	7	6	4.5	3.5	2.5	3.5	4.5	4.5	2.5	1.5	0	

Help reconstruct possible shapes of the fossil.

- a) Compute and plot the Hermite spline interpolants with natural boundary conditions, see 29e), for each of the components, i.e. find

$$p(t_i) = x_i, \quad p'(t_0) = p'(t_{26}) = 0; \quad q(t_i) = y_i, \quad q'(t_0) = q'(t_{26}) = 0$$

and plot the curve

$$\{(p(\xi), q(\xi)) : \xi \in [t_0, t_{26}]\}$$

for the two parametrizations

$$t_i = i; \quad t_0 = 0, \quad t_{i+1} = t_i + \sqrt{(x_{i+1} - x_i)^2 + (y_{i+1} - y_i)^2}.$$

The resulting curve will  $C^2$  smooth.

*Hint:* For an efficient implementation recall the Thomas-algorithm for tridiagonal matrices.

- b) Plot the B-spline basis of order  $p = 3$  for the knot vector

$$(0, 0, 0, 0, 1, 1, 2, 3, 3, 3, 4, 5, 5, 5, 6, 7, 8, 9, 10, 11, 11, 11, 12, 13, 13, 14, 15, 16, 16, 16, 16)$$

- c) Using b) plot the cubic B-spline curve through  $B_i = c_{i-1}$ .

Note how the choice of knots, in particular the multiplicities, affect the resulting contour.

(4 Points )

Send to [duesseldorf@ins.uni-bonn.de](mailto:duesseldorf@ins.uni-bonn.de)