



Numerical Algorithms

Winter term 2019/20
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Sheet 9

Submission on **Tuesday, 17.12.19** in class.

Exercise 1. (1D heat equation)

We consider a metal rod and its temperature distribution

$$y: [0, 1] \times [0, T] \longrightarrow \mathbb{R} \quad (9.1)$$

with initial condition $y(\cdot, 0) = y^0$. Additionally, we assume that we are able to control the heat flux of the metal rod at the end points. More precisely, we model $y(x, t)$ to satisfy the partial differential equation

$$y_t - y_{xx} = f \quad \text{in } [0, 1] \times [0, T] \quad (9.2)$$

$$-y_x(0, \cdot) = l \quad \text{in } [0, T] \quad (9.3)$$

$$y_x(1, \cdot) = r \quad \text{in } [0, T] \quad (9.4)$$

$$y(\cdot, 0) = y^0 \quad \text{in } [0, 1] \quad (9.5)$$

with control parameters $l(t)$, $r(t)$ and additional environmental influence $f(x, t)$.

We interpret $y(x, t) = y(t)(x) = y(t) \in V$ (f likewise), where y is now a function of time mapping into a function space V , which consists of functions defined on $[0, 1]$ (for instance $C[0, 1]$). Introducing the time steps $t_n = nT/N$ for $n = 0, \dots, N$ we define $y^n = y(t_n) \in V$, $f^n = f(t_n) \in V$, $l(t_n) = l^n \in \mathbb{R}$, $r(t_n) = r^n \in \mathbb{R}$.

- a) Use the implicit Euler scheme to derive the time-discretized formulation

$$y^n = y^{n-1} + \frac{T}{N}(f^n + y_{xx}^n), \quad n = 1, \dots, N \quad (9.6)$$

$$-y_x^n(0) = l^n, \quad n = 1, \dots, N \quad (9.7)$$

$$y_x^n(1) = r^n, \quad n = 1, \dots, N. \quad (9.8)$$

This is a system of N Poisson-like differential equations, which from now on we consider in their weak form. Next, we do a spatial discretization $V_h \subset V$ with basis functions $\{\phi_0, \dots, \phi_m\}$.

- b) Using the coefficient vector $\mathbf{y}^n \in \mathbb{R}^{m+1}$ with the Ansatz

$$y^n \approx \sum_{i=0}^m \mathbf{y}_i^n \phi_i, \quad (9.9)$$

derive the time-space discretized formulation

$$\left(M + \frac{T}{N}K\right) \mathbf{y}^n = \frac{T}{N}L^n + M\mathbf{y}^{n-1}, \quad n = 1, \dots, N. \quad (9.10)$$

Here, $M \in \mathbb{R}^{(m+1) \times (m+1)}$ is the mass matrix with $M_{ij} = \int \phi_i \phi_j$, $K \in \mathbb{R}^{(m+1) \times (m+1)}$ is the stiffness matrix with $K_{ij} = \int (\phi_i)_x (\phi_j)_x$, and $L^n \in \mathbb{R}^{m+1}$ is the load vector with $L_i^n = \int f^n \phi_i + \phi_i(0)l^n + \phi_i(1)r^n$.

- c) Repeat the derivation until (9.10), using the Crank-Nicholson scheme in time.

(15 points)